

**HAEF IB - MATH SL**  
**TEST - VECTORS**  
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**SOLUTIONS**

**PART A [45 marks]**

1. (a)  $\mathbf{u} \cdot \mathbf{v} = 8 + 3 + p$  (A1)  
 For equating scalar product equal to zero (M1)  
 $8 + 3 + p = 0$   
 $p = -11$  A1 N3
- (b)  $|\mathbf{u}| = \sqrt{2^2 + 3^2 + (-1)^2} = \sqrt{14}, 3.74$  (M1)  
 $q\sqrt{14} = 14$  A1  
 $q = \sqrt{14} (=3.74)$  A1 N2
2.  $p\mathbf{w} = p\mathbf{i} + 2p\mathbf{j} - 3p\mathbf{k}$  (seen anywhere) (A1)  
 attempt to find  $\mathbf{v} + p\mathbf{w}$  (M1)  
*eg*  $3\mathbf{i} + 4\mathbf{j} + \mathbf{k} + p(\mathbf{i} + 2\mathbf{j} - 3\mathbf{k})$   
 collecting terms  $(3 + p)\mathbf{i} + (4 + 2p)\mathbf{j} + (1 - 3p)\mathbf{k}$  A1  
 attempt to find the dot product (M1)  
*eg*  $1(3 + p) + 2(4 + 2p) - 3(1 - 3p)$   
 setting **their** dot product equal to 0 (M1)  
*eg*  $1(3 + p) + 2(4 + 2p) - 3(1 - 3p) = 0$   
 simplifying A1  
*eg*  $3 + p + 8 + 4p - 3 + 9p = 0, 14p + 8 = 0$   
 $P = -0.571 \left( -\frac{8}{14} \right)$  A1 N3
3. (a)  $\vec{AB} = \begin{pmatrix} 1 \\ -3 \end{pmatrix}, \vec{OR} = \begin{pmatrix} x \\ 3-3x \end{pmatrix}$  A1A1 N2
- (b)  $\vec{AB} \cdot \vec{OR} = x - 3(3 - 3x)$  A1  
 $\vec{AB} \cdot \vec{OR} = 0 \quad (10x - 9 = 0)$  M1  
 R is  $\left( \frac{9}{10}, \frac{3}{10} \right)$  A1A1 N2

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4. (a)  $\vec{PQ} = \begin{pmatrix} 5 \\ -3 \end{pmatrix}$  A1A1 N2

(b) Using  $\mathbf{r} = \mathbf{a} + t\mathbf{b}$

$$\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 1 \\ 6 \end{pmatrix} + t \begin{pmatrix} 5 \\ -3 \end{pmatrix}$$
A2A1A1 N4

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5. (a)  $\vec{AB} = \vec{OB} - \vec{OA} = \begin{pmatrix} 1 \\ 5 \\ 3 \end{pmatrix} - \begin{pmatrix} 3 \\ 2 \\ 1 \end{pmatrix}$  (M1)

$$\vec{AB} = \begin{pmatrix} -2 \\ 3 \\ 2 \end{pmatrix}$$
A2 N3

(b) Using  $\mathbf{r} = \mathbf{a} + t\mathbf{b}$

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 3 \\ 2 \\ 1 \end{pmatrix} + t \begin{pmatrix} -2 \\ 3 \\ 2 \end{pmatrix} \text{ or } \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 1 \\ 5 \\ 3 \end{pmatrix} + t \begin{pmatrix} -2 \\ 3 \\ 2 \end{pmatrix}$$
A1A1A1 N3

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6. (a)  $\vec{CD} = \vec{OD} - \vec{OC}$  (A1) (C1)

(b)  $\vec{OA} = \frac{1}{2}\vec{CD}$   
 $= \frac{1}{2}(\vec{OD} - \vec{OC})$  (A1) (C1)

(c)  $\vec{AD} = \vec{OD} - \vec{OA}$   
 $= \vec{OD} - \frac{1}{2}(\vec{OD} - \vec{OC})$  (A1)  
 $= \frac{1}{2}\vec{OD} + \frac{1}{2}\vec{OC}$  (A1) (C2)

*Note: Deduct [1 mark] (once only) if appropriate vector notation is omitted.*

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7. evidence of equating vectors (M1)  
 eg  $L_1 = L_2$

for any **two** correct equations A1A1

eg  $2 + s = 3 - t$ ,  $5 + 2s = -3 + 3t$ ,  $3 + 3s = 8 - 4t$

attempting to solve the equations (M1)

finding **one** correct parameter ( $s = -1$ ,  $t = 2$ ) A1

the coordinates of T are (1, 3, 0) A1 N3

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**PART B [45 marks]**

8. (a) (i) evidence of combining vectors (M1)

eg  $\vec{AB} = \vec{OB} - \vec{OA}$  (or  $\vec{AD} = \vec{AO} + \vec{OD}$  in part (ii))

$$\vec{AB} = \begin{pmatrix} 2 \\ -4 \\ -2 \end{pmatrix} \quad \text{A1 N2}$$

(ii)  $\vec{AD} = \begin{pmatrix} 2 \\ k-5 \\ -2 \end{pmatrix} \quad \text{A1 N1}$

(b) evidence of using perpendicularity  $\Rightarrow$  scalar product = 0 (M1)

e.g.  $\begin{pmatrix} 2 \\ -4 \\ -2 \end{pmatrix} \bullet \begin{pmatrix} 2 \\ k-5 \\ -2 \end{pmatrix} = 0$

$4 - 4(k-5) + 4 = 0 \quad \text{A1}$

$-4k + 28 = 0$  (accept any correct equation clearly leading to  $k = 7$ )  $\text{A1}$

$k = 7 \quad \text{AG N0}$

(c)  $\vec{AD} = \begin{pmatrix} 2 \\ 2 \\ -2 \end{pmatrix} \quad \vec{BC} = \begin{pmatrix} 1 \\ 1 \\ -1 \end{pmatrix} \quad \text{(A1)A1}$

evidence of correct approach eg  $\vec{OC} = \vec{OB} + \vec{BC}, \begin{pmatrix} 3 \\ 1 \\ 2 \end{pmatrix} + \begin{pmatrix} 1 \\ 1 \\ -1 \end{pmatrix}, \begin{pmatrix} x-3 \\ y-1 \\ z-2 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \\ -1 \end{pmatrix} \text{ (M1)}$

$$\vec{OC} = \begin{pmatrix} 4 \\ 2 \\ 1 \end{pmatrix} \quad \text{A1 N3}$$

(d) **METHOD 1**

choosing appropriate vectors,  $\vec{BA}, \vec{BC} \quad \text{(A1)}$

finding the scalar product  $\text{M1}$

eg  $-2(1) + 4(1) + 2(-1), 2(1) + (-4)(1) + (-2)(-1)$

$\cos \hat{ABC} = 0 \quad \text{A1 N1}$

**METHOD 2**

$\vec{BC}$  parallel to  $\vec{AD}$  (may show this on a diagram with points labelled)  $\text{R1}$

$\vec{BC} \perp \vec{AB}$  (may show this on a diagram with points labelled)  $\text{R1}$

$\hat{ABC} = 90^\circ$

$\cos \hat{ABC} = 0 \quad \text{A1 N1}$

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9. (a) (i) Evidence of approach

$$\text{eg } \vec{JQ} = \begin{pmatrix} 0 \\ 7 \\ 10 \end{pmatrix} - \begin{pmatrix} 6 \\ 0 \\ 0 \end{pmatrix}, \vec{JQ} = \vec{JO} + \vec{OQ} \quad \text{M1}$$

$$\vec{JQ} = \begin{pmatrix} -6 \\ 7 \\ 10 \end{pmatrix} \quad \text{AG} \quad \text{N0}$$

$$(ii) \vec{MK} = \begin{pmatrix} 6 \\ -7 \\ 10 \end{pmatrix} \quad \text{A1} \quad \text{N1}$$

$$(b) (i) \mathbf{r} = \begin{pmatrix} 6 \\ 0 \\ 0 \end{pmatrix} + t \begin{pmatrix} -6 \\ 7 \\ 10 \end{pmatrix} \text{ or } \mathbf{r} = \begin{pmatrix} 0 \\ 7 \\ 10 \end{pmatrix} + t \begin{pmatrix} -6 \\ 7 \\ 10 \end{pmatrix} \quad \text{A2} \quad \text{N2}$$

*Note: Award A1 if "r = " is missing.*

$$(ii) \text{ Evidence of choosing correct vectors } \begin{pmatrix} -6 \\ 7 \\ 10 \end{pmatrix}, \begin{pmatrix} 6 \\ -7 \\ 10 \end{pmatrix} \quad (\text{A1})(\text{A1})$$

Evidence of calculating magnitudes (A1)(A1)

$$\text{eg } \sqrt{(-6)^2 + 7^2 + 10^2} = \sqrt{185} \quad \sqrt{6^2 + (-7)^2 + 10^2} \\ = \sqrt{185}$$

$$\begin{pmatrix} -6 \\ 7 \\ 10 \end{pmatrix} \cdot \begin{pmatrix} 6 \\ -7 \\ 10 \end{pmatrix} = -36 - 49 + 100 \quad (= 15) \quad (\text{accept } -15) \quad (\text{A1})$$

For evidence of substitution into the correct formula M1

$$\text{eg } \cos \theta = \frac{15}{\sqrt{185}\sqrt{185}} \left( = \frac{15}{185} = 0.0811 \right)$$

$$\left( \text{accept } \frac{-15}{\sqrt{185}\sqrt{185}} \right)$$

$$\theta = 1.49 \text{ (radians), } 85.3^\circ \quad \text{A1} \quad \text{N4}$$

(c) **METHOD 1**

Geometric approach (M1)

Valid reasoning A2

eg diagonals bisect each other,  $\vec{OD} = \vec{OM} + \frac{1}{2}\vec{MK}$

Calculation of mid point (A1)

eg  $\left(\frac{6+0}{2}, \frac{0+7}{2}, \frac{0+10}{2}\right)$

$\vec{OD} = \begin{pmatrix} 3 \\ 3.5 \\ 5 \end{pmatrix}$  (accept (3,3.5,5)) A1 N3

**METHOD 2**

Correct approach (M1)

eg  $\begin{pmatrix} 6 \\ 0 \\ 0 \end{pmatrix} + t \begin{pmatrix} -6 \\ 7 \\ 10 \end{pmatrix} = \begin{pmatrix} 0 \\ 7 \\ 10 \end{pmatrix} + s \begin{pmatrix} 6 \\ -7 \\ 10 \end{pmatrix}$

Two correct equations A1

eg  $6 - 6t = 6s, 7t = 7 - 7s, 10t = 10s$

Attempt to solve (M1)

One correct parameter

$s = 0.5 \quad t = 0.5$  A1

$\vec{OD} = \begin{pmatrix} 3 \\ 3.5 \\ 5 \end{pmatrix}$  (accept (3, 3.5, 5)) A1 N3

**METHOD 3**

Correct approach (M1)

eg  $\begin{pmatrix} 0 \\ 7 \\ 10 \end{pmatrix} + t \begin{pmatrix} -6 \\ 7 \\ 10 \end{pmatrix} = \begin{pmatrix} 0 \\ 7 \\ 0 \end{pmatrix} + s \begin{pmatrix} 6 \\ -7 \\ 10 \end{pmatrix}$

Two correct equations A1

eg  $-6t = 6s, 7 + 7t = 7 - 7s, 10 + 10t = 10s$

Attempt to solve (M1)

One correct parameter

$s = 0.5 \quad t = -0.5$  A1

$\vec{OD} = \begin{pmatrix} 3 \\ 3.5 \\ 5 \end{pmatrix}$  (accept (3, 3.5, 5)) A1 N3

10. (a) speed =  $\sqrt{3^2 + 4^2 + 10^2}$  (M1)  
 $= \sqrt{125} = 5\sqrt{5}, 11.2$ , (metres per minute) A1 N2

(b) Let the velocity vector be  $\begin{pmatrix} a \\ b \\ c \end{pmatrix}$

Finding a velocity vector A2

eg  $\begin{pmatrix} 3 \\ 16 \\ 39 \end{pmatrix} = \begin{pmatrix} -5 \\ 10 \\ 23 \end{pmatrix} + 2 \begin{pmatrix} a \\ b \\ c \end{pmatrix}, \begin{pmatrix} 3 \\ 16 \\ 39 \end{pmatrix} - \begin{pmatrix} -5 \\ 10 \\ 23 \end{pmatrix}$

Dividing by 2 to give  $\begin{pmatrix} 4 \\ 3 \\ 8 \end{pmatrix}$  A1

$\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} -5 \\ 10 \\ 23 \end{pmatrix} + t \begin{pmatrix} 4 \\ 3 \\ 8 \end{pmatrix}$  AG N0

(c) (i) At Q,  $\begin{pmatrix} 3 \\ 2 \\ 7 \end{pmatrix} + t \begin{pmatrix} 3 \\ 4 \\ 10 \end{pmatrix} = \begin{pmatrix} -5 \\ 10 \\ 23 \end{pmatrix} + t \begin{pmatrix} 4 \\ 3 \\ 8 \end{pmatrix}$  (M1)

Setting up one correct equation A1

eg  $3 + 3t = -5 + 4t, 2 + 4t = 10 + 3t, 7 + 10t = 23 + 8t$

$t = 8$  (A1)

Correct answer A1

eg after 8 minutes, 13:08 N3

(ii) Substituting for  $t$  (M1)

$\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 3 \\ 2 \\ 7 \end{pmatrix} + 8 \begin{pmatrix} 3 \\ 4 \\ 10 \end{pmatrix}, \text{ or } \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} -5 \\ 10 \\ 23 \end{pmatrix} + 8 \begin{pmatrix} 4 \\ 3 \\ 8 \end{pmatrix}$

$x = 27, y = 34, z = 87$  or  $(27, 34, 87)$ , or  $\begin{pmatrix} 27 \\ 34 \\ 87 \end{pmatrix}$  A1 N2

(d) For choosing **both** direction vectors  $d_1 = \begin{pmatrix} 3 \\ 4 \\ 10 \end{pmatrix}$  and  $d_2 = \begin{pmatrix} 4 \\ 3 \\ 8 \end{pmatrix}$  (A1)

$d_1 \cdot d_2 = 104, |d_1| = \sqrt{125}, |d_2| = \sqrt{89}$  (A1)(A1)(A1)

$\cos \theta = \frac{104}{\sqrt{125} \sqrt{89}} = 0.98601\dots$  A1

$\theta = 0.167$  (radians) (accept  $\theta = 9.59^\circ$ ) A1 N3